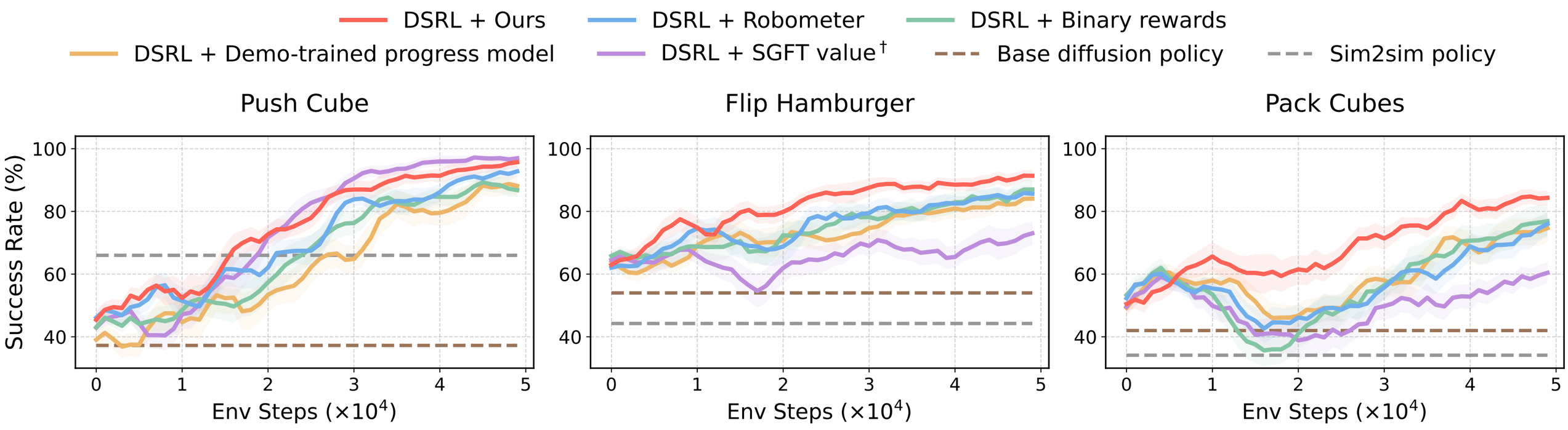

DSRL + Ours
DSRL + Robometer
DSRL + Binary rewards
DSRL + Demo-trained progress model
DSRL + SGFT value†
Base diffusion policy
Sim2sim policy
Push Cube
Flip Hamburger
Pack Cubes
Success Rate (%)
100
80
60
40
0
1
2
3
4
5
Env Steps (×10^4)